

Lecture 8

Last time

- ▷ Better guarantees for convex f
- ▷ Strongly convex

Today

- ▷ Accelerated gradient descent.
- ▷ Lower bounds

Everything we will see today was originally developed by Nesterov.



So far we have seen that GD yields

L -smooth	$f(x_k) - \min f \leq O\left(\frac{1}{k}\right)$
L -smooth + μ -strongly convex	$f(x_k) - \min f \leq O\left(\left(\frac{k-1}{k+1}\right)^{2k}\right)$

\uparrow condition number $\frac{L}{\mu}$.

Question: Can we have a faster algorithm that only have access to gradients? Yes! We'll see an alg for L -smooth in HW you'll handle the other case.

In 1983, Nesterov published a paper with a mysterious method.

It updates two sequences:

$$\lambda_{k+1} \leftarrow (1 + \sqrt{1 + 4\lambda_k^2}) / 2$$

$$y_{k+1} \leftarrow x_k - \frac{1}{L} \nabla f(x_k)$$

$$x_{k+1} \leftarrow y_{k+1} + \frac{(\lambda_k - 1)}{\lambda_{k+1}} (y_{k+1} - y_k).$$

To gain some intuition let's watch a video.

In this class we will analyze this method.

Theorem: Let f be a convex function with L -Lipschitz gradient. Then for any $\min x^*$,

$$f(y_k) - \min f \leq \frac{2L \|x_0 - x^*\|^2}{k^2}.$$

Proof: We start with two lemmas

Lemma 1: The seq of λ_k satisfies
 $\lambda_{k+1}^2 - \lambda_{k+1} = \lambda_k^2$ and for any $k \geq 1$

$$\lambda_k \geq \frac{k+1}{2}.$$

Proof: Identity follows from the formula.
 For the second part

$$\begin{aligned} \lambda_{k+1} &= \frac{1 + \sqrt{1 + 4\lambda_k^2}}{2} \geq \frac{1}{2} + \frac{\sqrt{4\lambda_k^2}}{2} \geq \frac{1}{2} + \lambda_k \\ &\geq \frac{k+1}{2} + \lambda_0 \quad \square \end{aligned}$$

Lemma 2: For any u, v

$$f\left(u - \frac{1}{2L} \nabla f(u)\right) - f(v) \leq -\frac{1}{2L} \|\nabla f(u)\|^2 + \nabla f(u)^T (u - v).$$

Proof: Use convexity and DL

$$\begin{aligned} f\left(u - \frac{1}{2L} \nabla f(u)\right) - f(v) &\leq f\left(u - \frac{1}{2L} \nabla f(u)\right) - (f(u) + \nabla f(u)^T (v - u)) \\ &\leq -\frac{1}{2L} \|\nabla f(u)\|^2 + \nabla f(u)^T (u - v). \quad \square \end{aligned}$$

Our goal is to use these lemmas to find a recursion of $\delta_k = f(y_k) - \min f$.

Apply Lemma 2 with $u = x_k$, $v = y_k$

$$\begin{aligned} \delta_{k+1} - \delta_k &= f(y_{k+1}) - f(y_k) \leq -\frac{1}{2L} \|\nabla f(x_k)\|^2 + \nabla f(x_k)^T (x_k - y_k) \\ &\stackrel{\text{(\smiley)}}{\leq} -\frac{L}{2} \|y_{k+1} - x_k\|^2 - L (y_{k+1} - x_k)^T (x_k - y_k). \end{aligned}$$

Apply Lemma 2 with $u = x_k$, $v = x^*$

$$\begin{aligned} \delta_{k+1} &= f(y_{k+1}) - \min f \leq -\frac{1}{2L} \|\nabla f(x_k)\|^2 + \nabla f(x_k)^T (x_k - x^*) \\ &\stackrel{\text{(\heartsuit)}}{\leq} -\frac{L}{2} \|y_{k+1} - x_k\|^2 - L (y_{k+1} - x_k)^T (x_k - x^*). \end{aligned}$$

Adding up $(\lambda_k - 1) \text{(\smiley)} + \text{(\heartsuit)}$ gives

$$\begin{aligned} \lambda_k \delta_{k+1} - (\lambda_k - 1) \delta_k &\leq -\frac{L\lambda_k}{2} \|y_{k+1} - x_k\|^2 \\ &\quad - L (y_{k+1} - x_k)^T (\lambda_k x_k - (\lambda_k - 1)y_k - x^*) \end{aligned}$$

Multiplying by λ_k gives

$$\begin{aligned}
& \lambda_k^2 \delta_{k+1} - (\lambda_k^2 - \lambda_k) \delta_k \leq \\
& - \frac{L}{2} \left[\| \lambda_k (y_{k+1} - x_k) \|^2 + 2 \lambda_k (y_{k+1} - x_k)^T (\lambda_k x_k - (\lambda_k - 1) y_k - x^*) \right] \\
& = - \frac{L}{2} \left(\| \lambda_k (y_{k+1} - x_k) + \lambda_k x_k - (\lambda_k - 1) y_k - x^* \|^2 \right. \\
& \quad \left. - \| \lambda_k x_k - (\lambda_k - 1) y_k - x^* \|^2 \right)
\end{aligned}$$

By def

$$x_{k+1} = y_{k+1} + \frac{\lambda_k - 1}{\lambda_{k+1}} (y_{k+1} - y_k)$$

\Updownarrow

$$\lambda_{k+1} x_{k+1} - (\lambda_{k+1} - 1) y_{k+1} = \lambda_k y_{k+1} - (\lambda_k - 1) y_k.$$

$$\begin{aligned}
(\lambda_k^2 \delta_{k+1} - \lambda_{k-1}^2 \delta_k) &= - \frac{L}{2} \left(\| \lambda_{k+1} x_{k+1} - (\lambda_{k+1} - 1) y_{k+1} - x^* \|^2 \right. \\
&\quad \left. - \| \lambda_k x_k - (\lambda_k - 1) y_k - x^* \|^2 \right)
\end{aligned}$$

$u_{k+1} :=$

$u_k :=$

Summing up from $k=1$ to $k=T-1$ yields

$$\lambda_{T-1}^2 \delta_T - \lambda_0^2 \delta_1 \leq - \frac{L}{2} (\|u_T\|^2 - \|u_1\|^2)$$

$$\begin{aligned}
 &\leq \frac{L}{2} \|\lambda_1 x_1 - (\lambda_1 - 1) y_1 - x^*\|^2 \\
 &= \frac{L}{2} \|x_1 - x^*\|^2.
 \end{aligned}$$

Then

$$\delta_T \leq \frac{L \|x_1 - x^*\|^2}{2 \lambda_{T-1}^2} \leq \frac{2L \|x_1 - x^*\|^2}{T^2}$$

We just prove that there is an alg. significantly faster than GD! \square

AGD with 1000 iterations gives the "same" error than GD with 1000.000!