

# Lecture 4

Sep/05/2024

Last time

- 2nd-order optimality cond.
- Basic convexity

## Agenda

- Characterization smooth convex.
- Subgradients.

## Lemma (First-order characterization of convexity)

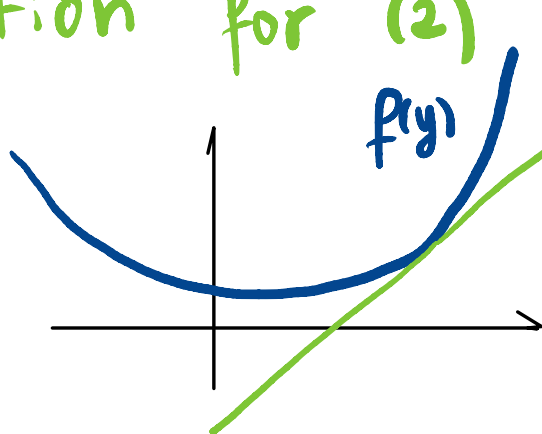
Suppose that  $f: \mathbb{R}^d \rightarrow \mathbb{R}$  is differentiable.  
Then, the following are equivalent:

(1)  $f$  is convex.

(2)  $\forall x, y \in \mathbb{R}^d \quad f(y) \geq f(x) + \langle \nabla f(x), y-x \rangle$

(3)  $\forall x, y \quad \langle \nabla f(x) - \nabla f(y), x-y \rangle \geq 0.$

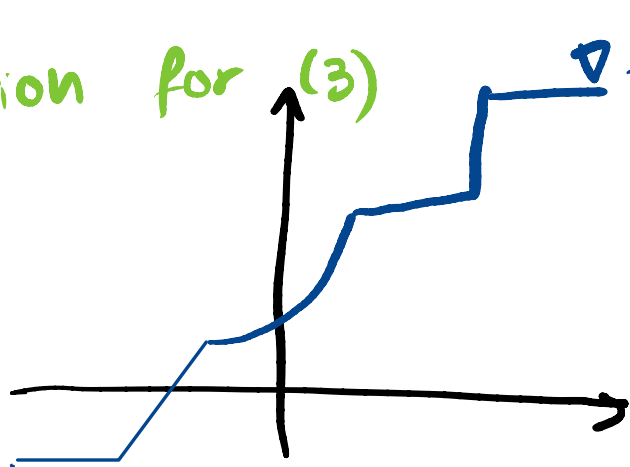
Intuition for (2)



$$f(x) + \langle \nabla f(x), y-x \rangle$$

↳ supports the epigraph

# Intuition for (3)



In 1D the function is monotone.

Proof: (1)  $\Rightarrow$  (2) Let  $x, y \in \mathbb{R}^d$  and  $t \in (0, 1]$   
 Convexity ensures that

$$f(x + \lambda(y-x)) \leq (1-\lambda)f(x) + \lambda f(y)$$

$\Leftrightarrow$

$$\underline{f(x + \lambda(y-x)) - f(x)} \leq f(y) - f(x)$$

Taking  $\lambda \rightarrow 0 \Rightarrow \langle \nabla f(x), x-y \rangle + f(x) \leq f(y)$ .

(2)  $\Leftarrow$  (1) Let  $x, y \in \mathbb{R}$ ,  $\lambda \in [0, 1]$  and

$$z_t = (1-t)x + t y$$

$$\Rightarrow f(x) \geq f(z_t) + \langle \nabla f(z_t), x - z_t \rangle \quad (1)$$

$$f(y) \geq f(z_t) + \langle \nabla f(z_t), y - z_t \rangle \quad (2)$$

$\Rightarrow (1-t)(1) + t(2)$  gives

$$(1-t)f(x) + tf(y) \geq f(z_t) + \langle \nabla f(z_t), \underbrace{(1-t)x + ty}_{= z_t} - z_t \rangle$$

$$\geq f(z_t).$$

$$\begin{aligned}
 (2) \Rightarrow (3) \quad & f(x) \geq f(y) + \nabla f(y)^T (x-y) \\
 & + f(y) \geq f(x) + \nabla f(x)^T (y-x) \\
 \hline
 & 0 \geq (\nabla f(x) - \nabla f(y))^T (y-x)
 \end{aligned}$$

(3)  $\Rightarrow$  (2) Define  $\varphi(t) = f(x + t(y-x))$

$$\begin{aligned}
 \text{Then } f(y) &= \varphi(1) = \varphi(0) + \int_0^1 \varphi'(t) dt \\
 &= \varphi(0) + \varphi'(0) + \int_0^1 [\varphi'(t) - \varphi'(0)] dt \\
 &= f(x) + \nabla f(x)^T (y-x) + \underbrace{\int_0^1 \underbrace{[\varphi'(t) - \varphi'(0)]}_{\geq 0} dt}_{\geq 0} \\
 &= f(x) + \nabla f(x)^T (y-x) + \int_0^1 \nabla f(x + t(y-x))^T (y-x) dt \\
 &\geq f(x) + \nabla f(x)^T (y-x)
 \end{aligned}$$

□

Lemma 2<sup>nd</sup>-order characterization

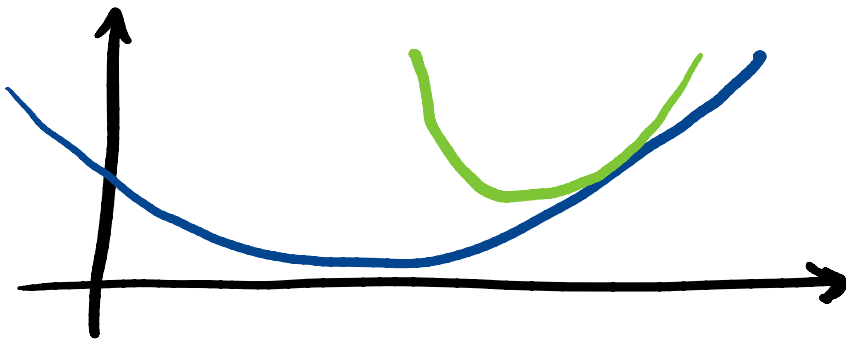
Assume  $f$  twice differentiable. Then,

$f$  is convex  $\Leftrightarrow \nabla^2 f(x) \succeq 0 \quad \forall x.$

$$\begin{aligned}
 & s^T \nabla^2 f(x) s \geq 0 \quad \forall s, \\
 & \lambda_{\min}(\nabla^2 f(x)) \geq 0.
 \end{aligned}$$

## Intuition

Second order model never curves down!

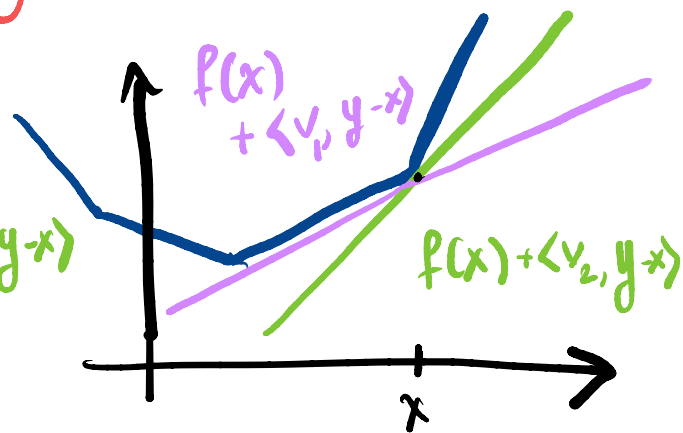
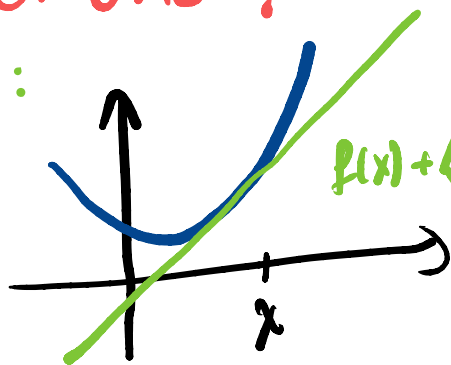


Proof Exercise.

□

Question: How can we assess optimality for general convex functions?

Idea:

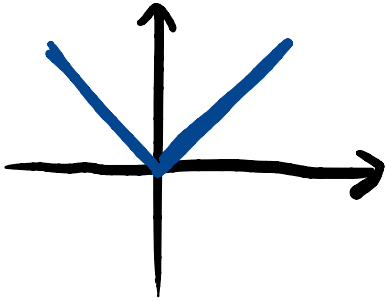


Def: Consider a convex function  $f: \mathbb{R}^d \rightarrow \mathbb{R}$ . The subdifferential of  $f$  at  $x$  is

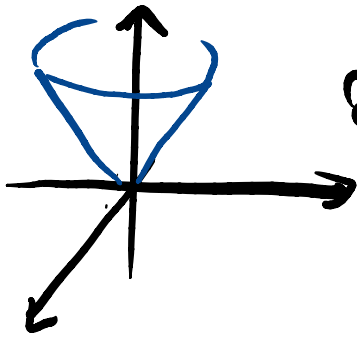
$$\partial f(x) = \{ v \mid \forall y \in \mathbb{R}^d \quad f(y) \geq f(x) + \langle v, y-x \rangle \}$$

# Examples

1.  $f(x) = |x|$

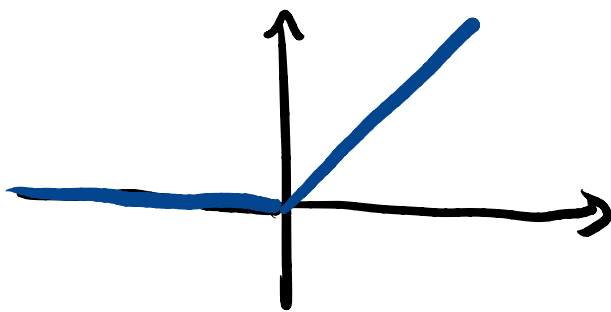


2.  $f(x) = \|x\|$

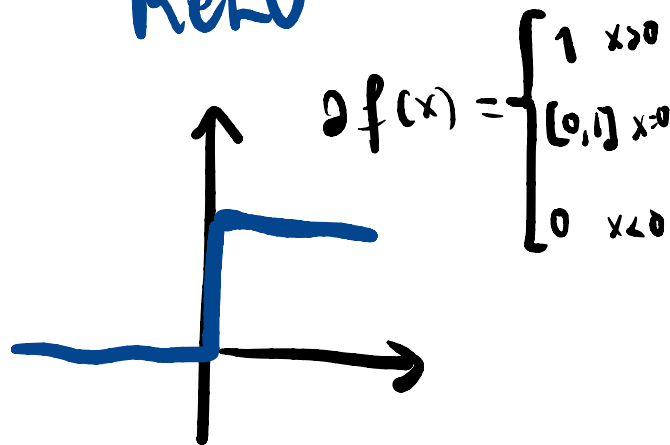


$$\partial f(x) = \begin{cases} \frac{x}{\|x\|} & \|x\| > 0 \\ \{y \mid \|y\| \leq 1\} & \|x\| = 0 \end{cases}$$

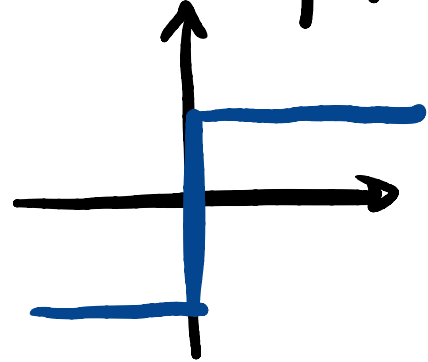
3.  $f(x) = \max\{0, x\}$



ReLU



$$\partial f(x) = \begin{cases} 1 & x > 0 \\ [-1, 1] & x = 0 \\ -1 & x < 0 \end{cases}$$



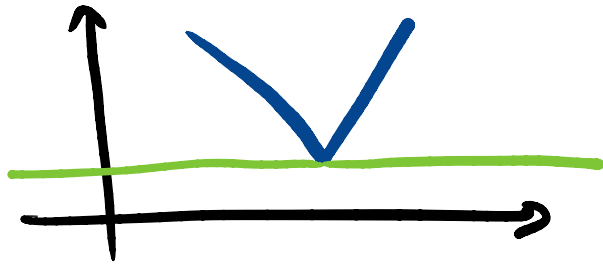
What do we just gained? general

Theorem: Optimality cond for convex func.

Suppose  $f: \mathbb{R}^d \rightarrow \mathbb{R}$  is convex. Then

$x^*$  is a minimizer iff  $0 \in \partial f(x^*)$ .

Intuition



✓ Nothing goes under.

Proof: Assume  $x^*$  is a minimizer.

$$f(x^*) + \langle 0, y - x^* \rangle \leq f(y) \quad \forall y.$$

Assume that  $0 \in \partial f(x)$ . □

Proposition: Subdifferential calculus

Suppose that  $f_1, f_2: \mathbb{R}^d \rightarrow \mathbb{R}$  are convex functions. Then the following holds

1. (Sums)  $\partial (f_1 + f_2)(x) = \partial f_1(x) + \partial f_2(x)$ .
2. (Chain rule) If  $A: \mathbb{R}^n \rightarrow \mathbb{R}^d$  linear

$$\partial (f_1 \circ A)(x) = A' \partial f_1(Ax).$$

3. (Scalings)

$$\partial (\alpha f_1)(x) = \alpha \partial f_1(x).$$

4. (Max) For all  $x$ , define  $M(x) = \{i \mid f_i(x) = \max\{f_1(x), f_2(x)\}\}$ .

$$\partial \max\{f_1, f_2\}(x) = \text{conv}\{g \in \partial f_i \mid i \in M(x)\}.$$

convex hull



5. (Smooth functions) Assume that  $f_i$  is diff at  $x$ .

$$\partial f_i(x) = \{\nabla f_i(x)\}.$$

← This one you should prove

What did we gain?

A way to compute subdiff. for complicated functions!