

Lecture 15

Last time

- ▷ Stochastic Gradient Descent
- ▷ Examples
- ▷ Analysis

Today

- ▷ Analysis continued
- ▷ Convex guarantees
- ▷ Extensions

Theorem Suppose $f: \mathbb{R}^d \rightarrow \mathbb{R}$ is L -smooth and $g(x, z)$ is an unbiased estimator such that

$$\mathbb{E}[\|g(x, z) - \nabla f(x)\|^2] \leq \sigma^2 \quad \forall x.$$

Then the iterates of stochastic gradient descent with $0 < \alpha_k < 2/L$ satisfy

$$\mathbb{E} \left[\min_{k \leq T} \|\nabla f(x_k)\|_2^2 \right] \leq \frac{(f(x_0) - \min f) + \frac{\sigma^2 L}{2} \sum_{k=0}^T \alpha_k^2}{\sum_{k=0}^T \alpha_k \left(1 - \frac{L\alpha_k}{2}\right)}$$

Relevant properties of the expectation

- ▷ Linearity

Given X_1, \dots, X_n r.v. and constants $\lambda_1, \dots, \lambda_n$, we have

$$\mathbb{E} \left[\sum_{i=1}^n \lambda_i X_i \right] = \sum \lambda_i \mathbb{E} X_i.$$

▷ Tower law

Given two random variables X, Y

$$\mathbb{E}_X \left[\mathbb{E}[Y|X] \right] = \mathbb{E}[Y]$$

↑
conditional
expectation

Proof: By the Taylor Approximation Theorem

$$\begin{aligned} f(x_{k+1}) &\leq f(x_k) + \nabla f(x_k)^T (x_{k+1} - x_k) + \frac{L}{2} \|x_{k+1} - x_k\|^2 \\ &= f(x_k) - \alpha_k \nabla f(x_k)^T g_k + \frac{L\alpha_k^2}{2} \|g_k\|^2 \end{aligned}$$

Conditioning on x_k

$$\begin{aligned} \mathbb{E}[f(x_{k+1}) | x_k] &\leq f(x_k) - \alpha_k \mathbb{E}[\nabla f(x_k)^T g_k | x_k] \\ &\quad + \frac{L\alpha_k^2}{2} \mathbb{E}[\|g_k\|^2 | x_k] \\ &\stackrel{\text{Linearity}}{\downarrow} = f(x_k) - \alpha_k \nabla f(x_k)^T \mathbb{E}[g_k | x_k] \\ &\quad + \frac{L\alpha_k^2}{2} \mathbb{E}[\|g_k\|^2 | x_k] \end{aligned}$$

random
because of z_k

(♡)

$$\begin{aligned} &\leq f(x_k) - \alpha_k \|\nabla f(x_k)\|^2 \\ &\quad + \frac{L\alpha_k^2}{2} \left[\sigma^2 + \|\nabla f(x_k)\|^2 \right] \\ &= f(x_k) - \left(\alpha_k + \frac{L\alpha_k^2}{2} \right) \|\nabla f(x_k)\|^2 \\ &\quad + \frac{L\alpha_k^2}{2} \sigma^2. \end{aligned}$$

By Tower Law

$$\mathbb{E} [f(x_{k+1})] \leq \mathbb{E} \left[f(x_k) - \left(\alpha_k + \frac{L\alpha_k^2}{2} \right) \|\nabla f(x_k)\|^2 + \frac{L\alpha_k^2}{2} \sigma^2 \right]$$

By recursively applying this formula

$$\mathbb{E} [f(x_{T+1})] \leq \mathbb{E} f(x_0) - \sum_{k=0}^T \left(\alpha_k - \frac{L\alpha_k^2}{2} \right) \mathbb{E} \|\nabla f(x_k)\|^2 + \sum_{k=0}^T \frac{L\alpha_k^2}{2} \sigma^2$$

The result follows from reordering and using the fact that

$$\mathbb{E} \left[\min_{k \leq T} \|\nabla f(x_k)\|^2 \right] \sum_{k=0}^T \left(\alpha_k - \frac{L\alpha_k^2}{2} \right)$$

$$\leq \sum_{k=0}^T \left(\alpha_k - \frac{L\alpha_k^2}{2} \right) \mathbb{E} [\|\nabla f(x_k)\|^2]. \quad \square$$

Consequences

$$\text{If } \alpha_k = \frac{1}{L\sqrt{T+1}} \Rightarrow 1 - \frac{L\alpha_k}{2} \geq \frac{1}{2}.$$

Thus we derive

$$\begin{aligned} \mathbb{E} \left[\min_{k \leq T} \|\nabla f(x_k)\|^2 \right] &\leq \frac{(f(x_0) - \min f) + \frac{\sigma^2}{2L}}{\frac{1}{2} \sqrt{T+1}} \\ &= O\left(\frac{1}{\sqrt{T}}\right). \end{aligned}$$

By Jensen's inequality

$$\Rightarrow \mathbb{E} \min_{k \leq T} \|\nabla f(x_k)\| = O(T^{-1/4}).$$

This is rather slow, however it improves when we have convexity.

Convex guarantees

Theorem Consider the same setting as the previous Theorem, further assume that $\alpha_k = \alpha \leq \frac{1}{L}$, f is convex and $x^* \in \text{argmin } f$. Then

$$\mathbb{E} \left[\min_{k \leq T} \{ f(x_k) - f(x^*) \} \right] \leq \frac{\|x_0 - x^*\|^2}{2\alpha(k+1)} + \alpha\sigma^2.$$

In particular if $\alpha = \frac{1}{\sqrt{T+1}}$ and $T \geq L^2$

$$\mathbb{E} \left[\min_{k \leq T} \{ f(x_k) - f(x^*) \} \right] \leq \frac{\|x_0 - x^*\|^2 + 2\sigma^2}{2\sqrt{k+1}}$$

Proof When $\alpha \leq \frac{1}{L}$, (10) gives

$$\mathbb{E} [f(x_{k+1}) | x_k] \leq f(x_k) - \frac{\alpha}{2} \|\nabla f(x_k)\|^2 + \frac{\alpha\sigma^2}{2}$$

By convexity

By Assumption

$$\mathbb{E} [\|g(x, z)\|^2 | x] - \sigma^2 \leq \|\nabla f(x)\|^2$$

$$\leq f(x^*) - \nabla f(x_k)^T (x^* - x_k) - \frac{\alpha}{2} \mathbb{E} [\|g(x_k, z)\|^2 | x_k] + \alpha\sigma^2$$

$$\leq f(x^*) - \mathbb{E} [g(x_k, z)^T (x^* - x_k) + \frac{\alpha}{2} \|g(x_k, z)\|^2 | x_k]$$

Using that

$$+ \alpha\sigma^2$$

$$\|x_{k+1} - x^*\|^2 = \|x_k - x^* - \alpha g_k\|^2 = \|x_k - x^*\|^2 + 2\alpha g_k^T (x^* - x_k) + \alpha^2 \|g_k\|^2$$

$$\hookrightarrow \leq f(x^*) - \mathbb{E} \left[\frac{1}{2\alpha} [\|x_{k+1} - x^*\|^2 - \|x_k - x^*\|^2] \right] + \alpha\sigma^2$$

By Tower law

$$\mathbb{E} [f(x_{k+1}) - f(x^*)] \leq \frac{1}{2\alpha} \mathbb{E} [\|x_{k+1} - x^*\|^2 - \|x_k - x^*\|^2] + \alpha \sigma^2$$

Once more the result follows by summing up and dividing by T . \square

Remark

▷ The rate above is of the order $O(\frac{1}{\sqrt{T}})$, exactly like the rate for nonsmooth convex optimization.

▷ In HW 4 you'll show the same rate for stochastic nonsmooth convex opt. There, we will have $g(x, z)$ s.t.
 $\mathbb{E} [g(x, z)] \in \partial f(x)$.

Extensions

Acceleration?

The noise dominates and leads to slow convergence. Best known rate

$$O\left(\frac{L \|x_0 - x^*\|^2}{T^2} + \frac{\sigma^2}{\sqrt{T}}\right).$$

Randomized coordinate descent

Assume our oracle is

(\smile) $i \sim \text{Unif}(\{1, \dots, d\})$
 $g(x, i) = d \cdot \frac{\partial f}{\partial x_i}(x) \cdot e_i.$

The analysis above yields a guarantee but we can do better.

Theorem. Assume $f: \mathbb{R}^d \rightarrow \mathbb{R}$ L -smooth.
Then SGD with (\smile) and $\alpha_k = \frac{1}{Ld}$
yields

$$\mathbb{E} \left[\min_{k \leq T} \|\nabla f(x_k)\|^2 \right] \leq \frac{2Ld(f(x_0) - \min)}{T}.$$

Proof Indeed this oracle gives descent
At iter k ,

$$\begin{aligned} f(x_{k+1}) &\leq f(x_k) + \nabla f(x_k)^T (x_{k+1} - x_k) \\ &\quad + \frac{L}{2} \|x_{k+1} - x_k\|^2 \\ &= f(x_k) - \frac{1}{Ld} d \frac{\partial f}{\partial x_i}(x_k) \cdot \nabla f(x_k)^T e_i \\ &\quad + \frac{1}{2Ld^2} \left(d \frac{\partial f}{\partial x_i}(x_k) \right)^2 \\ &= f(x_k) - \frac{1}{2L} \left(\frac{\partial f}{\partial x_i}(x_k) \right)^2. \end{aligned}$$

Taking expectations

$$\begin{aligned}\mathbb{E}[f(x_{k+1})] &\leq \mathbb{E}[f(x_k)] - \frac{1}{2L} \mathbb{E}\left[\left(\frac{\partial f}{\partial x_i}(x_k)\right)^2\right] \\ &= \mathbb{E}[f(x_k)] - \frac{1}{2L} \frac{1}{d} \mathbb{E}[\|\nabla f(x_k)\|^2]\end{aligned}$$

$$\mathbb{E}\left[\left(\frac{\partial f(x)}{\partial x_i}\right)^2 \middle| x\right] = \frac{1}{d} \|\nabla f(x_k)\|^2.$$

By recursively applying the formula above, we obtain

$$\mathbb{E}[f(x_{T+1})] \leq \mathbb{E}[f(x_0)] - \frac{1}{2Ld} \sum_{k=0}^T \mathbb{E}[\|\nabla f(x_k)\|^2].$$

Reordering and multiplying by $\frac{1}{T}$, yields

$$\mathbb{E}\left[\min_{k \leq T} \|\nabla f(x_k)\|^2\right] \leq \frac{2Ld}{T} (f(x_0) - \min f).$$

This is the same rate as in the deterministic case. □

Extensions to greedy and cyclic rules can be found in [Nottini, ICML'15] and [Beck, Tetruashvili, SIOP'15].

Stochastic Variance Reduced Gradient (SVRG)

Recall the finite sum problem

$$\min_x \frac{1}{n} \sum_{i=1}^n f_i(x).$$

The SVRG reads as follows

Algorithm

Set $\tilde{x}_0 \leftarrow x_0$

for $i = 0, \dots$

$y_0 \leftarrow \tilde{x}$

for $j = 0, \dots, 2d$

Draws $l \sim \text{Unif}(\{1, \dots, n\})$

$g_j \leftarrow \nabla f(\tilde{x}_i) + \nabla f_l(y_j) - \nabla f_l(\tilde{x})$

$y_{j+1} \leftarrow y_j - \alpha g_j$

end for

$\tilde{x}_{i+1} \leftarrow \frac{1}{2d+1} \sum_{j=0}^{2d} y_j.$

end for

outer loop

inner loop

Theorem: Assume $f: \mathbb{R}^d \rightarrow \mathbb{R}$ L -smooth
 μ -strongly convex. Then, if α
sufficiently small $\gamma \in (0, 1)$.

$$\mathbb{E}[f(\tilde{x}_k) - \min f] \leq \gamma^k [f(\tilde{x}_0) - \min f].$$

Proof: [Johnson, Zhang 2013]

□